

```

*****
*****
**  M E G A S Q U I R T - 2 0 0 1 - V3.000
**
**  (C) 2002 - B. A. Bowling And A. C. Grippo
**
**  This header must appear on all derivatives of this code.
**
*****
*****

```

```

;-----
; Version 3.000
;-----
; Version 2.986 upgraded to Version 3.000
;
;-----
; Version 2.986
;-----
; Modified boot_r12 file to raise the LVI trip point.
; Fill unused RAM locations with $32, an illegal opcode to force a reset. Done
; to prevent flash erasure if code ever gets into a runaway state - for protection only.
; Put in interlocks to prevent VE/Constant section flash erasure unless specifically
; invoked by a flash burn command.
; Put in Odd-fire RPM averaging (Willitte) for odd-fire engines.
; Added new calculation structure to code - same calculation as HI-RES code, but results
; are in 0.1 millisecond units. Calculation overflow fixed.
; Flyback damping code installed - jumper port X0 for INJ1 and jumper port X1 for INJ2.
; Fixed display of WARMCOR variable (no flickering).
; Inhibit PWM mode while cranking.
; Made "ADC" into "ADD in ADC interrupt section (Tom D) to properly perform the sum
; without a carry.
; Perform 12 ms time compare for re-enabling of tach IRQ interrupt (fix for random tach problem) -
; original trial time of 20 ms too long (Magnus Bjelk fix - also for high/low byte check).
; Moved after-start enrichment to increment after "N" tach pulses have occurred,
; with N being the number of cylinders. This will lengthen the afterstart enrichment
; time by an amount scaled by the number of cylinders (Tom).
; Fix display of barometer correction (no screen flicker if 100% barometer is selected).
; Fixed IRQ counter to work properly for NCYL above 8 cylinders.
;
;-----
; Version 2.0
;-----
; Acceleration Enrichment Cold Multiplier added - now cold accel enrichment in form of a + b * x
; Barometer Correction Selection Mode put in Config13
; Bootloader Bug (lda vs ldx) fixed for this version
; RPM Calc made more efficient and bug fix for RPM exclusion values (Konstantin)
; Changed Flood clear value to 0.3 ms
; Added the "Guy ROM Offset" to fix the bootloader erase problem
; Added Embedded Code revision number SCI query command ("Q")
; Fixed SCI "C" transfer mode
; Added Alpha-N mode
; Added O2 target voltage constant and DIY-WB O2 sensor support, and bit for Odd-Fire Mode
; (no odd-code mode in embedded code yet).
; Fixed Battery voltage correction roll-over problem.
; Fixed Lininterp problem with large negative numerator spans
; Fixed "sticky" decel bit
; Added both MPX4115 and MPX4250 KPA and Barofac tables in flash - selected by config register

```

```
; Prime Pulses and Adjustable RPM for entry into closed-loop added 4/2/02
;
;-----
; Version 1.5
;-----
; O2 closed-loop mode added 11/1/01
;
;-----
; Version 1.01
;-----
; Inverted Injector driver MC33151 implemented:
; To change output from inverted to non-inverted, change
; all of the bset and bclr calls for inject1 and inject2 to their inverse.
```

```
.header 'MegaSquirt'
;.base 10t
.pagewidth 130
.pagelength 90
;.set simulate
```

```
.nolist
    include "gp32.equ"
.list
    org     ram_start
    include "megasquirt.h"
```

```
*****
**
** Main Routine Here - Initialization and main loop
**
** Note: Org down 128 bytes below the "rom_start" point
**       because of erase bug in bootloader routine
**
** Note: Items commented out after the Start entry point are
**       taken care of in the Boot_R12.asm code
**
*****
```

```
    org     {rom_start + 128}
Start:
;   *** Note - uncomment this code if you do not use the Bootloader to initialize ***
;   clra
;       sta     copctl
;       mov     #%00000001,config2
;       mov     #%00001001,config1
;       mov     #%00000001,config1
;       ldhx    #ram_last+1           ; Set the stack Pointer
;       txs                                ; to the bottom of RAM
```

```
;PLLSet:
;       bclr    BCS,pctl             ; Select external Clock Reference
;       bclr    PLLON,pctl           ; Turn Of PLL
;       mov     #$02,pctl            ; Set P and E Bits
;       mov     #$C0,pmrs            ; Set L
;       mov     #$03,pmsh            ; Set N (MSB)
;       mov     #$84,pmsl            ; Set N (LSB)
;       bset    AUTO,pbwc
;       bset    PLLON,pctl           ; Turn back on PLL
```

```
;PLLwait:
;   brclr LOCK,pbwc,PLLwait
;   bset  BCS,pctl
```

;When the operand is immediate, the value is contained in the bytes immediately following the instruction. That is, the instruction is not followed by a memory location, it is followed by a number to be used for the instruction. In this case, the effective address of the instruction is specified by the # sign and implicitly points to the byte following the opcode. The immediate value is limited to either one or two bytes, depending on the size of the register involved in the instruction.

```
;
; Set all RAM to known value - for code runaway protection.
; If there is ever a code runaway, and processor tries
; executing this as an opcode ($32) then a reset will occur.
;
```

```
ldhx #ram_start ;Point to start of RAM
```

ClearRAM:

```
lda    #$32          ; This is an illegal op-code - cause reset if executed
sta    ,x             ;Set RAM location
aix    #1             ;advance pointer
cphx   #ram_last+1    ;done ?
bne    ClearRAM       ;loop back if not
```

;A pound sign (#) before a number indicates an immediate operand. The default base is decimal.
;Hexadecimal numbers are represented by a dollar sign (\$) preceding the number. Binary numbers are represented by a percent sign (%) preceding the number.

; Set up the port data-direction registers

```
lda    #%00000000
sta    ddrb           ; Set as inputs (ADC will select which channel later)
lda    #%00110000     ; Turn off injectors (inverted output)
sta    portd
lda    #%11110000
sta    ddrd           ; Outputs for injector
clr    porta
lda    #%11111111
sta    ddra           ; Outputs for Fp and Idle
lda    #$00
sta    portc
lda    #%00011111     ; ** Was 11111111
sta    ddrc           ; Outputs for LED
lda    #%00000001     ; Serial Comm Port
sta    ddre
```

; Set up the Real-time clock Timer (TIM2)

```
MOV    #Timerstop,t2sc ; Stop Timer so it can be set up
mov    #$00,T2MODH      ;Destination ← Source
mov    #$B8,T2MODL      ; set timer modulus register to 184 decimal
mov    #T2SC0_No_PWM,T2SC0 ; make this normal port output (PWM MODE is #$5E)
mov    #$00,T2CH0H
mov    #$00,T2CH0L
MOV    #Timergo,T2SC     ; set timer prescaler to divide by 4
```

; Set up the PWM for the Injector (for current limit mode)

```
MOV    #Timerstop,t1sc    ; Stop Timer so it can be set up
mov     #$00,T1MODH        ;Destination ← Source
mov     #$64,T1MODL        ; set timer modulus register to 100 decimal
mov     #T1SCX_NO_PWM,T1SC0 ; make this normal port output (PWM MODE is #$5E)
mov     #T1SCX_NO_PWM,T1SC1 ; make this normal port output (PWM MODE is #$5E)
mov     #$00,T1CH0H
mov     INJPWM,T1CH0L
mov     #$00,T1CH1H        ;Destination ← Source
mov     INJPWM,T1CH1L
```

; Set up SCI port

```
lda     #$12                ; This is 9600 baud w/ the osc frequency selected
sta     scbr
bset    ensci,scc1          ; Enable SCI Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are
unaffected.
```

```
bset    RE,SCC2             ; Enable receiver
bset    SCRIE,SCC2          ; Enable Receive interrupt
lda     SCS1                ; Clear SCI transmitter Empty Bit
clr     txcnt
clr     txgoal
```

; Set up Interrupts

```
mov     #%00000100,INTSCR;Enable IRQ
```

; Set up RAM Variable

```
clr     mms
clr     ms
clr     tenth
clr     secl
clr     sech
lda     #$FF
clr     squirt
lda     #$32
sta     pw
clr     engine
clr     rpmph
clr     rpmch
clr     rpm
clr     old_rpm1
clr     flocker
lda     #$00
sta     pwcalc
sta     pw
clr     pwrn1
clr     pwrn2
lda     #$FF
sta     last_tps
clr     egocount

lda     #$BB
sta     baro
sta     map
sta     mat
```

```

sta  clt
sta  tps
sta  batt

lda  #$64
sta  aircor
sta  vecurr
sta  barocor
sta  warmcor
sta  egocorr
sta  tpsfuelcut
clr  gammae
lda  #$46
sta  map
lda  #$65
sta  baro
clr  tpsaccel

clr  igncount

```

```

; Fire up the ADC, and perform one conversion to get the baro value
lda  #%01110000 ; Set up divide 8 and internal bus clock source
sta  adclk
lda  #%00000000 ; Select one conversion, no interrupt, AD0
sta  adscr
brclr coco,adscr,* ; wait until conversion is finished

lda  adr
sta  baro ; Store value in Barometer

clr  adsel ; Clear the channel selector

```

```

TURN_ON_INTS:
cli ; Turn on all interrupts now

```

; Load the constants (VE Table, etc) from Flash to RAM - the program uses the RAM values

```

clrh
clrx
XXVV:
lda  VETABLE,x ; This is the FLASH table for all inputs
sta  VE,x ; This is the RAM-based table - this is what is used by pgm.
incx
cbeq #80,XXXV
bra  XXVV
XXXV:

```

; Load the Flash Programming Routine into RAM - it will sit there until invoked

```

clrh
clrx
NEXTRAM:
lda  ERASE_N_BURN,x ; Programmer routine to be copied
sta  BURNER,x ; RAM Location that keep the burner code
incx

```

```

cbeqx #$FF,DONE_LOAD_BURN
bra  NEXTRAM

```

DONE_LOAD_BURN:

```

*****

```

```

**

```

```

** Prime Pulse - Shoot out one priming pulse of length PRIMEP

```

```

**

```

```

*****

```

```

lda  PRIMEP
beq  LOOPER      ; Branch around priming pulse if zero

sta  pw
sta  pw2
bset  fuelp,porta
clr  pwrune1
clr  pwrune2
bset  sched1,squirt ;Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.

bset  inj1,squirt
bset  sched2,squirt
bset  inj2,squirt
bset  running,engine

```

```

*****

```

```

***** MAIN EVENT LOOP *****

```

```

*****

```

LOOPER:

```

*****

```

```

**

```

```

** Correction Factor Lookup Table Access

```

```

**

```

```

** Perform table lookup for barometer and air density correction factors,
** and performs coolant temperature conversion from counts to degrees F

```

```

**

```

```

** All tables are pre-computed for all 256 different values
** and stored in FLASH

```

```

**

```

```

** Note: Coolant temperature is in degrees F plus 40 - this allows
** unsigned numbers for full temperature range

```

```

**

```

```

**

```

```

*****

```

```

clrh

```

```

lda  config11
and  #$01
bne  TurboMap

```

NaMap:

```

lda  baro
tax
lda  BAROFAC4115,x
sta  tmp11      ; Barometer Correction Gamma

```

;.....tmp1,...,tmp19 = Temporary storage.

```
lda  map
tax
lda  KPAFACTOR4115,x
sta  kpa          ; Manifold Air Pressure in Kilopascals

lda  config13      ; Check if we use baro correction mode (bit=1) or not (bit=0)
bit  #$08          ; Use BIT instead of brset because outside of zero-page
bne  NaBaroUse     ; Branch if the bit is set - we use the MAP-obtained barometer

lda  #$64
sta  barocor       ; Store 100% barometer correction (correction not used)
bra  CltCalc
```

NaBaroUse:

```
lda  tmp11          ; Use the saved MAP-derived barometer value
sta  barocor
bra  CltCalc
```

TurboMap:

```
lda  baro
tax
lda  BAROFAC4250,x
sta  tmp11         ; Barometer Correction Gamma
```

```
lda  map
tax
lda  KPAFACTOR4250,x
sta  kpa          ; Manifold Air Pressure in Kilopascals
```

lda config13 ; Check if we use baro correction mode (bit=1) or not (bit=0)among other thinks over and over again.

```
bit  #$08          ; Use BIT instead of brset because outside of zero-page
bne  TurboBaroUse  ; Branch if the bit is set - we use the MAP-obtained barometer
```

```
lda  #$64
sta  barocor       ; Store 100% barometer correction (correction not used)
bra  CltCalc
```

TurboBaroUse:

```
lda  tmp11          ; Use the saved MAP-derived barometer value
sta  barocor
```

CltCalc:

```
lda  clt
tax
lda  THERMFACTOR,x
sta  coolant      ; Coolant temperature in degrees F + 40
```

```
lda  mat
tax
lda  AIRDENFACTOR,x
sta  aircor       ; Air Density Correction Factor
```

**

** Fast Idle Comparison - fast idle set is coolant below FAST IDLE value

**

```
    lda    fastidle
    cmp    coolant
    bhi    SLOW_IDLE_SET
```

FAST_IDLE_SET:

```
    bclr   iasc,porta
    bra    RPM_COMP
```

SLOW_IDLE_SET:

```
    bset   iasc,porta    ;Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
```

**

** Computation of RPM

**

```
**  rpmk:rpmk+1
**  ----- = rpm
**  rpmph:rpmpl
```

**

** rpmk:rpmK+1 = RPM constant = (6,000 * (stroke/2))/ncyl

** rpmph:rpmpl = period count between IRQ pulsed lines, in 0.1 millisecond resolution

**

RPM_COMP:

```
    brclr  running,engine,LOOPER
    ldhx   rpmph
    beq     LOOPER
```

```
    pshh
    pula
    tsta
    beq     FAST_RPM_CALC
```

SLOW_RPM_CALC:

```
    clr    intacc1
    clr    intacc1+1
```

```
    sthx   intacc2
```

```
    ldhx   rpmk
    sthx   intacc1+2
```

```
    jsr    udvd32        ; 32 x 32 divide
    lda    intacc1+3      ; get 8-bit RPM result
    bra    RPM_CALC_DONE
```

FAST_RPM_CALC:

```
    lda    rpmk
    psha
    pulh
    lda    rpmk+1
    div                    ; A = (H:A) / X
```

RPM_CALC_DONE:

```
    sta    tmp1    ; Will move this later on...
```

; If odd-fire is set (bit zero of Config13), then average RPM values

```
    lda    config13
    and    #$01
    beq    NO_ODD_FIRE
```

YES_ODD_FIRE:

```
    lda    tmp1
    add    old_rpm1 ; this variable is updated in the IRQ section to latch last RPM
    rora
    sta    rpm
    bra    CHK_FOR_WENRCH
```

;.....tmp1,...,tmp19 = Temporary storage.

NO_ODD_FIRE:

```
    lda    tmp1
    sta    rpm
```

CHK_FOR_WENRCH:

```
    cmp    #$03    ; Check if we are cranking
    bhi    WARM_UP_ENRICH
```

**

** Cranking Mode

**

** Pulsewidth is directly set by the coolant temperature value of

** CWU (at -40 degrees) and CWH (at 165 degrees) - value is interpolated

**

CRANKING_SET:

```
    bset   crank,engine ;Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
    bclr   startw,engine
    bclr   warmup,engine
```

```
    lda    #155T ; 3 Volts comparison value for TPS - flood clear trigger
    cmp    tps
    bhi    INTERP_CRANK_PW
```

FLOOD_CLEAR:

```
    lda    #$03 ; 0.3 ms pulsewidth - just opening...
    sta    pwcalc
    jmp    LOOPER
```

INTERP_CRANK_PW:

```
    lda    #$00
    sta    tmp1
    lda    #205T ; 165 + 40 degrees (because of offset in lookup table)
    sta    tmp2
    mov    cwu,tmp3
    mov    cwh,tmp4
    mov    coolant,tmp5
    jsr    lininterp
    mov    tmp6,pwcalc
    jmp    LOOPER
```

**

** Warm-up and After-start Enrichment Section

**

** The Warm-up enrichment is a linear interpolated value from WWU (10 points)

** which are placed at different temperatures

**

** Method:

**

** 1) Perform ordered table search of WWU (using coolant variable) to determine

** which bin.

** 2) Perform linear interpolation to get interpolated warmup enrichment

**

** Also, the after-start enrichment value is calculated and applied here - it

** is an added percent value on top of the warmup enrichment, and it is applied

** for the number of ignition cycles specified in AWC. This enrichment starts

** at a value of AWEV at first, then it linearly interpolates down to zero

** after AWC cycles.

**

** 3) If (startw, engine is set) then:

** 4) compare if (awc < asecount) then:

** 5) x1=0, x2=AWC, y1=AWEV, y2=0, x=asecount, y=ASEenrichment

** 6) else clear startw bit in engine

**

WARM_UP_ENRICH:

brclr crank,engine,WUE1

bclr crank,engine

bset startw,engine ;Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.

bset warmup,engine

clr asecount

WUE1:

ldhx #WWURANGE

sthx tmp1

lda #\$09

sta tmp3

lda coolant

sta tmp4

jsr ORD_TABLE_FIND

WUE4:

clrh

lda tmp5

tax

lda WWU,x

sta tmp4

decx

lda WWU,x

sta tmp3

mov coolant,tmp5

jsr lininterp

mov tmp6,tmp12

; mov tmp6,warmcor

; lda warmcor

lda tmp12

cmp #\$64

bne ASE1

; Outside of warmup range - clear warmup enrichment mode

```
lda    #$64
sta    warmcor
bclr   startw,engine
bclr   warmup,engine
bclr   wled,portc
bra    ASE_FINAL
```

ASE1:

```
bset   wled,portc    ;Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
bset   warmup,engine
brclr  startw,engine,ASE_FINAL
lda    asecount
cmp    awc
bhi    ASE_END
```

ASE2:

```
clr    tmp1
mov     AWC,tmp2
mov     AWEV,tmp3
clr    tmp4
mov     asecount,tmp5
jsr     lininterp
lda     tmp6
bcs     ASE_RAIL
add     tmp12
sta     warmcor
bra     TAE
```

ASE_RAIL:

```
lda    #$FE
sta     warmcor      ; Rail warmcor value
bra     TAE
```

ASE_END:

```
bclr   startw,engine
```

ASE_FINAL:

```
mov     tmp12,warmcor
```

**

** Throttle Position Acceleration Enrichment

**

** Method is the following:

**

**

** ACCELERATION ENRICHMENT:

** If (tps < last_tps) goto DEACCELERATION_ENRICHMENT

** If (tps - last_tps) > tpsthresh and TPSAEN = 0 then (acceleration enrichment):

** {

** 1) Set acceleration mode

** 2) Continuously determine rate-of-change of throttle, and perform

** interpolation of TPSAQ values to determine acceleration

** enrichment amount to apply.

** }

** If (TPSACLK > TPSACKCMP) and TPSAEN is set then:

** {

```

** 1) Clear TPSAEN bit in engine
** 2) Set TPSACCEL to 100%
** 3) Go to EGO Delta Step Check Section
** }
**
**
** DEACCELERATION ENRICHMENT:
** If (last_tps - tps) > tpsthresh then (deacceleration fuel cut)
** {
**   If (TPSAEN = 1) then:
**   {
**     1) TPSACCEL = 100 percent (no acceleration)
**     2) Clear TPSAEN bit in ENGINE
**     3) Go to EGO Delta Step
**   }
**   If (RPM > 15 (corresponding to 1500 RPM)) then (fuel cut mode):
**   {
**     1) Set TPSACCEL value to TPSDQ
**     2) Set TPSDEN bit in ENGINE
**     3) Go to EGO Delta Step Check Section
**   }
** }
** else
** {
**   If (TPSDEN = 1) then
**   {
**     1) Clear TPSDEN bit in ENGINE
**     2) TPSACCEL = 100%
**     3) Go to EGO Delta Step Check Section
**   }
** }
**
*****

```

TAE:

```

sei
mov    tps,tmp1
mov    last_tps,tmp2
cli
lda    tmp1
cmp    tmp2
blo    TDE2

```

AE_CHK:

```

lda    tmp1
sub    tmp2
cmp    tpsthresh
blo    B_LO_CONT
brset  TPSAEN,ENGINE,AE_COMP_SHOOT_AMT

```

; Add in accel enrichment

```

lda    TPSAQ      ; start out using first element - will determine actual next time around
sta    TPSACCEL    ; Acceleration percent amount - used in later calculations
clr    TPSACLK
lda    TPSASYNC
sta    tpsackcmp    ; Shoot time comparison value
bset   TPSAEN,ENGINE ;Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
bclr   TPSDEN,ENGINE
bset   aled,portc
bclr   wled,portc

```

```

        jmp    MAE

;TDE2:  bra    TDE            ; Only to extend branch for assembler

; First, calculate Cold temperature add-on enrichment value from coolant value TPSACOLD,
; from -40 degrees to 165 degrees.
;
; Then determine cold temperature multiplier value ACCELMULT (in percent), from -40 degrees to 165 degrees.
;
; Next, Calculate Shoot amount (quantity) for acceleration enrichment from table.
; Find bins (between) for corresponding TPSDOT, and linear interpolate
; to find enrichment amount (from TPSAQ). This is continuously
; checked every time thru main loop while in acceleration mode,
; and the highest value is latched and used.
;
; The final acceleration applied is AE = Alookup(TPSDOT) * (ACCELMULT/100) + TPSACOLD

```

AE_COMP_SHOOT_AMT:

```

; First, the "added" amount based on cold temperatures
    lda    #$00    ; 0 -> - 40 degrees
    sta    tmp1
    lda    #205T    ; 165 + 40 degrees (because of offset in lookup table)
    sta    tmp2
    mov    TPSACOLD,tmp3    ; This is the amount at coldest
    mov    #$00,tmp4        ; no enrichment add-on at warm temperature
    mov    coolant,tmp5
    jsr    lininterp
    mov    tmp6,tmp13        ; result - save here temporarily

; Second, find the multiplier (ACCELMULT) amount based on cold temperatures
    lda    #$00    ; 0 -> - 40 degrees
    sta    tmp1
    lda    #205T    ; 165 + 40 degrees (because of offset in lookup table)
    sta    tmp2
    lda    ACMULT
    sta    tmp3    ; This is the amount at coldest
    mov    #100T,tmp4    ; 1.00 multiplier at 165 degrees
    mov    coolant,tmp5
    jsr    lininterp
    mov    tmp6,tmp14        ; result - save here temporarily

; Now the lookup table amount based on TPSDOT
    ldhx    #tpsdotrate
    sthx    tmp1
    lda    #$03
    sta    tmp3
    lda    tps
    sub    last_tps
    sta    tmp4    ; TPSDOT
    sta    tmp10    ; Save away for later use below
    jsr    ord_table_find

    clrh
    lda    tmp5
    tax

```

```

lda  TPSAQ,x
sta  tmp4
decx
lda  TPSAQ,x
sta  tmp3
lda  tmp10
sta  tmp5
jsr  lininterp ; tmp6 has the result
bra  FIND_TOTAL_A

```

; This is here to extend the jump range for the checks at the beginning (long-jumps)

B_LO_CONT:

```
bra  TAE_CHK_TIME
```

TDE2: bra TDE ; Only to extend branch for assembler

; Now, the final applied acceleration enrichment amount is $((TMP6 * tmp14)/100) + tmp13$

FIND_TOTAL_A:

```

lda  tmp6
tax
lda  tmp14
mul
pshx
pulh
ldx  #$64
div
bcs  UPPER_RAIL_AE
psha
pshh
pula
cmp  #$32
ble  NDA1
pula
inca
bra  ADD_TO_AE

```

NDA1:

```

pula
bra  ADD_TO_AE

```

UPPER_RAIL_AE:

```

lda  #200T ; Set to 20 milliseconds railed
bra  ADD_TO_AE

```

ADD_TO_AE:

```

add  tmp13 ; Add on the amount computed in cold temperature enrich above
sta  tmp6
cmp  TPSACCEL
blo  TAE_CHK_TIME
lda  tmp6 ; Replace with this higher value
sta  TPSACCEL

```

; Check if acceleration done

TAE_CHK_TIME:

```

brset TPSDEN,ENGINE,RST_ACCEL
lda  tpsack
cmp  tpsackcmp
blo  MAE

```

```

RST_ACCEL:
    bclr    TPSAEN,ENGINE
    lda     #$64
        sta     tpsfuelcut
    clr     TPSACCEL
    bclr    aled,portc
        bclr    TPSDEN,ENGINE

    bra     MAE

; deaccel
TDE:
    lda     tmp2
    sub     tmp1

    cmp     tpsthresh
    blo     TDE_CHK_DONE
    brclr   TPSAEN,ENGINE,TDE_CHK_FUEL_CUT
    lda     #$64
        sta     TPSFUELCUT
    clr     TPSACCEL
    bclr    TPSAEN,ENGINE
    bclr    aled,portc
        bclr    TPSDEN,ENGINE
    bra     MAE
TDE_CHK_FUEL_CUT:
    lda     rpm
    cmp     #$0F
    blo     MAE
    lda     TPSDQ
    sta     TPSFUELCUT
    bset    TPSDEN,ENGINE    ;Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
    bclr    TPSAEN,ENGINE
    bclr    aled,portc
    bra     MAE
TDE_CHK_DONE:
    brclr   TPSDEN,ENGINE,MAE
    bclr    TPSDEN,ENGINE
    lda     #$64
    sta     TPSFUELCUT
    clr     TPSACCEL
    bra     MAE

```

**

** Exhaust Gas Oxygen Sensor Measurement Section

**

** Steps are the following:

**

** If egodelta = 0 then goto skipo2

** If RPM < RPMOXLIMIT then goto skipo2

** If TPSAEN in ENGINE or TPSDEN in ENGINE are set, then goto skipo2

** If coolant < egotemp then goto skipo2

** If sech = 0 and secl < 30 seconds then got skipo2 (skip first 30 seconds)

** If tps > 3.5 volts then goto skipo2

**

** If egocount > egocountcmp

** {

```

** egocount = 0
** If ego > 26 (counts, or 0.5 Volts) then (rich)
** {
**     tmp = egocurr - egodelta
**     if tmp < egolimit then goto VETABLELOOKUP
**     egocorr = tmp
**     Why not use the values directly from FLASH? There are two reasons: it can be slower because we
might have to use longer memory addresses, and it is much more involved to write values back to FLASH. You can only
write to FLASH by first erasing it. You can only erase flash in 128-byte chunks. So to change one value we would have to
erase 128 bytes, then write 128 bytes, making at least an extra 254 steps (128 erases plus 128 writes minus the 2 we would
have done any ways)!. As well, coded delays need to be built in because the FLASH writes are physically slower than
writing to RAM. There are various tricks to minimize the number of erase/write cycles with queues and other techniques,
but it is way too complicated for our application.
**     goto VETABLELOOKUP
** }
** else (lean)
** {
**     tmp = egocorr + egodelta
**     if tmp > egolimit then goto VETABLELOOKUP
**     egocorr = tmp
**     goto VETABLELOOKUP
** }
** }
**
** skipo2:
** egocorr = 100%
** goto VETABLELOOKUP
**
**
**

```

MAE:

```

    lda    egodelta
    beq     SKIPO2
    lda     rpm
    cmp     RPMOXLIMIT ; Low-end of RPM
    blo     SKIPO2
    brset   TPSAEN,ENGINE,SKIPO2
    brset   TPSDEN,ENGINE,SKIPO2
    lda     coolant
    cmp     egotemp
    blo     SKIPO2
    lda     tps
    cmp     #$B2
    bhi     SKIPO2
    lda     sech
    bne     chk_o2_lag ; if high seconds set then we can check o2
    lda     secl
    cmp     #$1E ; 30 seconds threshold
    blo     SKIPO2

```

; Check if exceeded lag time - if so then we can modify egocorr

CHK_O2_LAG:

```

    lda     egocount
    cmp     egocountcmp
    blo     VETABLELOOKUP

```

; Check if rich/lean

```

    clr     egocount

```

```

lda    config13          ; Check if Narrow-band (bit=0) or DIY-WB (bit=1)
bit    #$02              ; Use BIT instead of brset because outside of zero-page
bne    WBO2TYPE          ; Branch if the bit is set

```

NBO2TYPE:

```

lda    ego
cmp    VOLTOXTARGET
blo    O2_IS_LEAN
bra    O2_IS_RICH

```

WBO2TYPE:

```

lda    ego
cmp    VOLTOXTARGET
blo    O2_IS_RICH
bra    O2_IS_LEAN

```

; rich o2 - lean out egocorr

O2_IS_RICH:

```

lda    #$64
sub    egolimit          ; Generate the lower limit rail point
sta    tmp2
lda    egocorr
sub    egodelta
sta    tmp1
cmp    tmp2
blo    VETABLELOOKUP ; railed at egolimit value
lda    tmp1
sta    egocorr
bra    VETABLELOOKUP

```

; lean o2 - richen egocorr

O2_IS_LEAN:

```

lda    #$64
add    egolimit          ; Generate the upper limit rail point
sta    tmp2

lda    egocorr
add    egodelta
sta    tmp1
cmp    tmp2
bhi    VETABLELOOKUP ; railed at egolimit value
lda    tmp1
sta    egocorr
bra    VETABLELOOKUP

```

; reset egocorr to 100%

SKIPO2:

```

lda    #$64
sta    egocorr
bra    VETABLELOOKUP

```

**

** VE 3-D Table Lookup

**Why not use the values directly from FLASH? There are two reasons: it can be slower
 **because we might have to use longer memory addresses, and it is much more involved to
 **write values back to FLASH. You can only write to FLASH by first erasing it. You can

**only erase flash in 128-byte chunks. So to change one value we would have to erase 128 bytes,
 **then write 128 bytes, making at least an extra 254 steps (128 erases plus 128 writes
 **minus the 2 we would have done any ways)!. As well, coded delays need to be built in
 **because the FLASH writes are physically slower than writing to RAM. There are various
 **tricks to minimize the number of erase/write cycles with queues and other techniques,
 **but it is way too complicated for our application.

**MegaSquirt's Volumetric Efficiency Table resides at zero page \$00A6 to \$00E5, and we exceed
 **the zero page at REQ_FUEL which lives at address \$0100 (because we now require
 **two bytes - \$01 and \$00 to address it). The last RAM variable, crankrpm
 **lives at \$01A5, leaving \$0200-\$01A6 = \$5A = 90 bytes for the stack and FLASH burner code.

**A few highly efficient instructions will only work with direct page operands.
 **These are: BSET, BCLR, BRSET and BRCLR. The MOV instruction requires one of
 **the operands to be in the direct page. Click here to see more details of the 68HC908 memory map.

**
 ** This is used to determine value of VE based on RPM and MAP
 ** The table looks like:

```

**      105 +....+....+....+....+....+....+
**      .....
**      100 +....+....+....+....+....+....+
**      ...
** KPA      ...
**      ...
**      35 +....+....+....+....+....+....+
**      5  15  25  35  45  55  65  75 RPM/100
**

```

**
 ** Steps:

- ** 1) Find the bracketing KPA positions via ORD_TABLE_FIND, put index in tmp8 and bounding values in tmp9(kpa1) and tmp10(kpa2)
- ** 2) Find the bracketing RPM positions via ORD_TABLE_FIND, store index in tmp11 and bounding values in tmp13(rpm1) and tmp14(rpm2)
- ** 3) Using the VE table, find the table VE values for tmp15=VE(kpa1,rpm1), tmp16=VE(kpa1,rpm2), tmp17 = VE(kpa2,rpm1), and tmp18 = VE(kpa2,rpm2)
- ** 4) Find the interpolated VE value at the lower KPA range :
 ** x1=rpm1, x2=rpm2, y1=VE(kpa1,rpm1), y2=VE(kpa1,rpm2) - put in tmp19
- ** 5) Find the interpolated VE value at the upper KPA range :
 ** x1=rpm1, x2=rpm2, y1=VE(kpa2,rpm1), y2=VE(kpa2,rpm2) - put in tmp11
- ** 6) Find the final VE value using the two interpolated VE values:
 ** x1=kpa1, x2=kpa2, y1=VE_FROM_STEP_4, y2=VE_FROM_STEP_5

 VETABLELOOKUP:

; First, determine if in Speed-density or Alpha-N mode. If in Alpha-N mode, then
 ; replace the variable "kpa" with the contents of "tps". This will not break anything, since
 ; this check is performed again when multiplying MAP against the enrichments, and
 ; the SCI version of the variable is MAP, not kpa

```

lda  config13      ; Check if in speed-density or Alpha-N mode
bit  #$04          ; Use BIT instead of brset because outside of zero-page

```

beq VE_STEP_1 ; Branch if the bit is clear

lda tps
sta kpa

VE_STEP_1:

ldhx #KPARANGEVEFLASH
sthx tmp1
lda #\$07
sta tmp3
lda kpa
sta tmp4
jsr ORD_TABLE_FIND
lda tmp1
lda tmp2
mov tmp5,tmp8 ;Index
mov tmp1,tmp9 ;X1
mov tmp2,tmp10 ;X2

VE_STEP_2:

ldhx #RPMRANGEVEFLASH
sthx tmp1
lda #\$07
sta tmp3
lda rpm
sta tmp4
jsr ORD_TABLE_FIND
mov tmp5,tmp11 ;Index
mov tmp1,tmp13 ;X1
mov tmp2,tmp14 ;X2

VE_STEP_3:

;TABLEWALK:

clrh
lda #\$08
psha
pulx
lda tmp8
deca
mul
add tmp11
deca
tax
lda VE,x
sta tmp15
incx
lda VE,x
sta tmp16
lda #\$08
psha
pulx
lda tmp8
mul
add tmp11
deca
tax
lda VE,x
sta tmp17

```

incx
lda  VE,x
sta  tmp18
jmp  VE_STEP_4

```

VE_STEP_4:

```

mov  tmp13,tmp1
mov  tmp14,tmp2
mov  tmp15,tmp3
mov  tmp16,tmp4
mov  rpm,tmp5
jsr  lininterp
mov  tmp6,tmp19

```

VE_STEP_5:

```

mov  tmp13,tmp1
mov  tmp14,tmp2
mov  tmp17,tmp3
mov  tmp18,tmp4
mov  rpm,tmp5
jsr  lininterp
mov  tmp6,tmp11

```

VE_STEP_6:

```

mov  tmp9,tmp1
mov  tmp10,tmp2
mov  tmp19,tmp3
mov  tmp11,tmp4
mov  kpa,tmp5
lda  kpa
jsr  lininterp
mov  tmp6,vecurr

```

**

** Computation of Fuel Parameters

**

** Remainders are maintained for hi-resolution calculations - results

** converted back to 100 microsecond resolution at end.

**

** (Warm * Tpsfuelcut)/100 = R1 + rem1/100

** (Barcor * Aircor)/100 = R2 + rem2/100

** ((R1 + rem1/100) * (R2 + rem2/100)) / 100 = R3 + rem3/100

** (EGO * MAP)/100 = R4 + rem4/100

** ((R3 + rem3/100) * (R4 + rem4/100)) /100 = R5 + rem5/100

** (VE * REQ_FUEL)/100 = R6 + rem6/100

** ((R5 + rem5/100) * (R6 + rem6/100)) = R7

**

**

**

** Note that GAMMAE only includes Warm, Tpsfuelcut, Barocor, and Aircor (EGO no longer included)

**

** Rationle on ordering: to prevent calculation overflow for boosted operations,

** the variables have been ordered in specific "pairs" in the calculation:

** EGO * MAP - when at WOT, EGO is set to 100%, so MAP can run up to 255% without overflow

** VE * REQ_FUEL - for boosted applications, REQ_FUEL tends to be low (below 10 ms) due to the

```

**          added fuel requirements (i.e. large injectors), so VE entries can
**          be well above 100%.
**

```

```

*****

```

WARMACCEL_COMP:

```

mov  warmcor,tmp10          ; Warmup Correction in tmp10
clr  tmp11                  ; tmp11 is zero
mov  tpsfuelcut,tmp12       ; tpsfuelcut in tmp12
clr  tmp13                  ; tmp13 is zero
jsr  Supernorm              ; do the multiply and normalization
mov  tmp10,tmp1             ; save whole result in tmp1
mov  tmp11,tmp2             ; save remainder in tmp2

mov  barocor,tmp10          ; tmp10 is barometer percent
clr  tmp11                  ; zero to tmp11
mov  aircor,tmp12           ; air temp correction % in tmp12
clr  tmp13                  ; tmp13 is zero
jsr  Supernorm              ; multiply and divide by 100
                                ; result in tmp10:tmp11
mov  tmp1,tmp12             ; move saved tmp1 into tmp12
mov  tmp2,tmp13             ; move saved tmp2 into tmp13
jsr  Supernorm              ; multiply/divide
mov  tmp10,tmp5             ; save whole result into tmp5
mov  tmp11,tmp6             ; save remainder into tmp6
lda  tmp10
sta  gammae

mov  egocorr,tmp10          ; closed-loop correction percent into tmp10
clr  tmp11                  ; remainder is zero
mov  kpa,tmp12              ; MAP into tmp12
clr  tmp13                  ; no remainder
jsr  Supernorm              ; do the multiply and divide

mov  tmp5,tmp12             ; take saved result in tmp5 and put into tmp12
mov  tmp6,tmp13             ; tmp6 into tmp13
jsr  Supernorm              ; mult/div
mov  tmp10,tmp3             ; result (whole) save in tmp3
mov  tmp11,tmp4             ; remainder result save in tmp4

mov  vecurr,tmp10           ; VE into tmp10
clr  tmp11                  ; no remainder value for VE
mov  REQ_FUEL,tmp12         ; req-fuel into tmp12
clr  tmp13                  ; no remainder
jsr  Supernorm              ; mult/div

mov  tmp3,tmp12             ; take previous result and put in tmp12
mov  tmp4,tmp13             ; again for remainder
jsr  Supernorm              ; multiply/divide

mov  tmp10,tmp11

```

```

*****

```

```

**
** Calculation of Battery Voltage Correction for Injector Opening Time
**

```

```

** Injector open time is implemented as a linear function of
** battery voltage, from 7.2 volts (61 ADC counts) to 19.2 volts (164 counts),
** with 13.2 volts (113 counts) being the nominal operating voltage

```

```

** INJOPEN = injector open time at 13.2 volts in mms
** BATTFAC = injector open adjustment factor 6 volts from 13.2V in mms

```

```

**
** + (INJOPEN + BATTFAC)
** + *
** + (INJOPEN)
** + *
** + (INJOPEN - BATTFAC)
** + *
** +
** ++++++
** 7.2V      13.2V      19.2

```

```

*****

```

```

BATT_CORR_COMP:

```

```

    lda  #61T
    sta  tmp1
    lda  #164T
    sta  tmp2
    lda  injopen
    add  battfac
    sta  tmp3
    lda  injopen
    sub  battfac
    sta  tmp4
    bpl  MBFF ; Check if minus condition
    clr  tmp4

```

```

MBFF:

```

```

    mov  batt,tmp5
    jsr  lininterp ; injector open time in tmp6

```

```

**
;   clr  tmp6
**

```

```

*****

```

```

** Calculation of Final Pulse Width

```

```

** The following equation is evaluated here:

```

```

**
** PWCALC = TMP6 + TMP11 + TPSACCEL - INJOCFUEL

```

```

** Note that INJOCFUEL (injected fuel during injector open and close) is currently a
** constant - eventually it will be a function
** of battery voltage.

```

```

*****

```

```

ADD_INJ_OFFSET:

```

```

    lda  tmp11
    add  tmp6
    bcs  MAX_PWM_ALLOWED
    add  TPSACCEL

```

```

        bcs    MAX_PWM_ALLOWED
sub     InjOCFuel
sta     pwcalc
jmp     FINISHED_PW_COMP

```

MAX_PWM_ALLOWED:

```

lda     #$FE
sta     pwcalc

```

FINISHED_PW_COMP:

```

jmp     LOOPER

```

```

*****
**
** * * * * Interrupt Section * * * *
**
** Following interrupt service routines:
** - Timer Overflow
** - ADC Conversion Complete
** - IRQ input line transistion from high to low
** - Serial Communication received character
** - Serial Communications transmit buffer empty (send another character)
**
*****

```

```

*****
**
** Timer Rollover - Occurs every 1/10 of a millisecond - main timing clock
**
**
** Generate time rates:
** 1/10 milliseconds
** 1 milliseconds
** 1/10 seconds
** seconds
**
** Also, in 1/10 millisecond section, turn on/off injector and
** check RPM for stall condition
** In milliseconds section, fire off ADC conversion for next channel (5 total),
** and wrap back when all channels done
**
*****

```

TIMERROLL:

```

;=====
;***** 0.1 millesecond section *****
;=====
        inc     mms          ; bump up 0.1 millisec variable

;===== Injector Firing Control =====
;===== Main Injector Control Logic =====
        brset   sched1,squirt,NEW_SQUIRT1
INJF1:
        brset   sched2,squirt,NEW_SQUIRT2
INJF2:
        brset   firing1,squirt,CHK_DONE_1

```

INJF3:

```
brset firing2,squirt,CHK_DONE_2
jmp CHECK_RPM
```

==== Injector #1 - Start New Injection ===

NEW_SQUIRT1:

```
bset firing1,squirt ; Turn on "firing" bit
bclr sched1,squirt ; Turn off schedule bit (is now current operation)
bset inj1,squirt ; Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
bset sled,portc ; squirt LED is ON
```

```
mov #$00,T1CH0H ;Destination ← Source
```

```
mov INJPWM,T1CH0L ;Destination ← Source
bset 7,PORTA ; ** Flyback Damper - turn on X0 for Inj1
bclr inject1,portd ;^* * * Turn on Injector #1 (inverted drive)
bra INJF1
```

==== Injector #2 - Start New Injection ===

NEW_SQUIRT2:

```
bset firing2,squirt ; Turn on "firing" bit
bclr sched2,squirt ; Turn off schedule bit (is now current operation)
bset inj2,squirt ; Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
bset sled,portc ; squirt LED is ON
```

```
mov #$00,T1CH1H ;Destination ← Source
mov INJPWM,T1CH1L ;Destination ← Source
bset 6,PORTA ; ** Flyback Damper - turn on X1 for Injector 2
bclr inject2,portd ;^* * * Turn on Injector #1 (inverted drive)
bra INJF2
```

==== Injector #1 - Check for end of Injection ===

CHK_DONE_1:

```
inc pwrn1
lda pwrn1
cmp pw
beq OFF_INJ_1
brset crank,engine,INJF3 ; do not perform PWM limiting when cranking
lda pwrn1
cmp INJPWMT
beq PWM_LIMIT_1
bra INJF3
```

OFF_INJ_1:

```
bclr firing1,squirt
bclr sched1,squirt
bclr inj1,squirt
bclr 7,PORTA ; ** Flyback Damper - turn off X0
bset inject1,portd ;^* * * Turn Off Injector #1 (inverted drive)
mov #Timerstop,T1SC ;Destination ← Source
mov #t1scx_NO_PWM,T1SC0
mov #Timergo_NO_INT,T1SC
bra INJF3
```

PWM_LIMIT_1:

```
mov #Timerstop,T1SC ;Destination ← Source
mov #T1SCX_PWM,T1SC0
mov #Timergo_NO_INT,T1SC
bra INJF3
```

==== Injector #2 - Check for end of Injection ===

CHK_DONE_2:

```
inc    pwrn2
lda    pwrn2
cmp    pw2
beq    OFF_INJ_2
    brset    crank,engine,CHECK_RPM ; do not perform PWM limiting when cranking
lda    pwrn2
cmp    INJPWMT
beq    PWM_LIMIT_2
    bra     CHECK_RPM
```

OFF_INJ_2:

```
bclr    firing2,squirt
bclr    sched2,squirt
bclr    inj2,squirt
    bclr    6,PORTA      ; ** Flyback Damper - turn off X1 (for Inj 2)
bset    inject2,portd ;^* * * Turn Off Injector #2 (inverted drive)
mov     #Timerstop,T1SC ;Destination ← Source
mov     #t1scx_NO_PWM,T1SC1
mov     #Timergo_NO_INT,T1SC
bra     CHECK_RPM
```

PWM_LIMIT_2:

```
mov     #Timerstop,T1SC ;Destination ← Source
mov     #T1SCX_PWM,T1SC1
mov     #Timergo_NO_INT,T1SC
bra     CHECK_RPM
```

=====Check RPM Section=====

CHECK_RPM:

```
brclr    running,engine,ENABLE_THE_IRQ ; Branch if not running right now
brset    firing1,squirt,CHK_RE_ENABLE
brset    firing2,squirt,CHK_RE_ENABLE
bclr    sled,portc    ; squirt LED is OFF - nothing is injecting
```

CHK_RE_ENABLE:

===== Check for re-enabling of IRQ input pulses

```
lda     rpmpb        ; Get high byte of last rpm interval
beq     RPMLOWBYTECHK ; If zero go ahead check for half interval
lda     rpmcl        ; Check current rpm interval
cmp     #128T        ; 12.8 milliseconds is maximum (half of 25.6 ms = 1 in rpmpb)
beq     REARM_IRQ    ; time to re-arm IRQ
bra     INCRPMER     ; Jump around rpm half interval check
```

RPMLOWBYTECHK:

```
lda     rpmpl        ; Load in the latched previous RPM value
lsra
cmp     rpmcl        ; Is it the same value as current RPM Counter?
bne     INCRPMER     ; If not then jump around this
```

REARM_IRQ:

bset ACK,INTSCR ; clear out any latched interrupts Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.

```
bclr    IMASK,INTSCR    ; enable interrupts again for IRQ
```

INCRPMER:

```
inc     rpmcl
bne     CHECK_MMS
inc     rpmch
lda     rpmch
cmp     #$64    ; If RPMPH is 100 (or RPMPeriod = 2.5 sec) then engine stalled
bne     CHECK_MMS

clr     engine    ; Engine is stalled, clear all in engine
bclr    fuelp,porta    ; Turn off fuel Pump
bclr    iasc,porta    ; Turn off IAC ** Bug Fix By Guy Hill **
clr     rpmch
clr     rpmcl
bclr    sled,portc    ; squirt LED is OFF
bclr    wled,portc    ; warmup LED is off
clr     pw          ; zero out pulsewidth
clr     rpm
bclr    IMASK,INTSCR    ; enable all IRQ interrupts
bra     CHECK_MMS
```

ENABLE_THE_IRQ:

```
bclr    IMASK,INTSCR    ; Enable IRQ
```

CHECK_MMS:

```
lda     mms
cmp     #$0A
bne     RTC_DONE
```

```
;=====
;***** millesecond section *****
;=====
```

MSEC:

```
inc     ms          ; bump up millisec
clr     mms
```

; Fire off another ADC conversion, channel is pointed to by ADSEL

```
lda     adsel
ora     #%01000000
sta     adscr
```

MSDONE:

```
lda     ms
cmp     #$64
bne     RTC_DONE
```

```
;=====
;***** 1/10 second section *****
;=====
```

ONETENTH:

```
inc     tenth
inc     tpsack
clr     ms
```

; Save current TPS reading in last_tps variable to ompute TPSDOT in acceleration
; enrichment section

```

lda    tps
sta    last_tps

lda    tenth
cmp    #$0A
bne    RTC_DONE

```

```

;=====
;*****seconds section*****
;=====
SECONDS:

```

```

clr    tenth
inc    secl      ; bump up second count
bne    RTC_DONE
inc    sech

```

```

RTC_DONE:
lda    T2SC
bclr   7,T2SC
rti

```

```

*****
**
** IRQ - Input trigger for new pulse event
**
** This line is connected to the input trigger (i.e TACH signal from ignition
** system), and schedules a new injector shot (injector actually opened in
** 1/10 timer section above)
**
*****

```

DOSQUIRT:

```

lda    igncount
bne    EGOBUMP   ; Only increment ase counter if cylinder count is zero
inc    asecount  ; Increment after-start enrichment counter

```

GOBUMP:

```

inc    egocount  ; Increment EGO step counter

```

```

lda    rpmch
sta    rpmph
lda    rpmcl
sta    rpmpl
clr    rpmch
clr    rpmcl

```

```

lda    rpm
sta    old_rpm1  ; Used in odd-fire code - save the last computed RPM for average

```

```

bset    fuelp,porta ; Turn on fuel Pump Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
bset    running,engine ; Set engine running value

```

```

brset    crank,engine,SCHED_SQUIRT ;Squirt on every pulse if cranking

```

```

inc    igncount  ; Check to see if we are to squirt or skip

```

```

lda    igncount
cmp    divider
beq    SCHED_SQUIRT
lda    igncount
cmp    #$0F    ; The maximum allowed - reset if match
bne    IRQ_EXIT
clr    igncount
bra    IRQ_EXIT

```

SCHED_SQUIRT:

```

bset    fuelp,porta    ; Turn on fuel Pump Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
bset    running,engine ; Set engine running value
clr     igncount

```

```

brset    crank,engine,SCHED_BOTH
lda     alternate
beq     SCHED_BOTH
inc     altcount
brset    0,altcount,SCHED_INJ2

```

SCHED_INJ1:

```

lda     pwcalc
sta     pw        ; latched calculated pulsewidth
clr     pwrn1     ; Running counter variable set to zero
bset    sched1,squirt ; Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
bset    inj1,squirt
bra     IRQ_EXIT

```

SCHED_INJ2:

```

lda     pwcalc
sta     pw2       ; latched calculated pulsewidth
clr     pwrn2     ; Running counter variable set to zero
bset    sched2,squirt
bset    inj2,squirt
bra     IRQ_EXIT

```

SCHED_BOTH:

```

lda     pwcalc
sta     pw        ; Same pulsewidth
sta     pw2       ; for both
clr     pwrn1     ; Running counter variable set to zero
bset    sched1,squirt
bset    inj1,squirt ; Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
5, ... 0) in location M. All other bits in M are unaffected.

clr     pwrn2     ; Running counter variable set to zero
bset    sched2,squirt
bset    inj2,squirt

```

IRQ_EXIT:

```

bset    ACK,INTSCR    ; Flush out any new interrupts pending
bset    IMASK,INTSCR  ; Disable IRQ interrupts
bset    IRQF,INTSCR   ; Set bit n (n = 7, 6, 5, ... 0) in location M. All other bits in M are unaffected.
rti

```

```

**
** ADC - Interrupt for ADC conversion complete
**
*****
ADCDONE:
    pshh      ; Do this because processor does not stack H

    clrh

; Store previous values for derivative
    lda    adsel
    tax
    lda    map,x
    sta    lmap,x ; Store the old value

    lda    adr    ; Load in the new ADC reading
    add    map,x  ; Perform (map + last_map)/2 averaging (for all ADC readings) - bug fix
    rora
    sta    map,x  ; MAP is entry point, offset is loaded in index register

    lda    adsel
    inca
    cmp    #$06
    bne    ADCPTR
    clra
ADCPTR:
    sta    adsel

    pulh
    rti

*****
**
** SCI Communications
**
** Communications is established when the PC communications program sends
** a command character - the particular character sets the mode:
**
** "A" = send all of the realtime variables via txport.
** "V" = send the VE table and constants via txport (128 bytes)
** "W"<+<offset>+<newbyte> = receive new VE or constant byte value and
** store in offset location
** "B" = jump to flash burner routine and burn VE/constant values in RAM into flash
** "C" = Test communications - echo back SECL
** "Q" = Send over Embedded Code Revision Number (divide number by 10 - i.e. $21T is rev 2.1)
**
*****
IN_SCI_RCV:
    pshh
    lda    SCS1  ; Clear the SCRF bit by reading this register

    lda    txmode ; Check if we are in the middle of a receive new VE/constant
    cmp    #$05
    beq    TXMODE_5
    cmp    #$06
    beq    TXMODE_6

    lda    SCDR  ; Get the command byte
    cmp    #$41  ; Is the recieve character a big "A" -> Download real-time variables?

```

```

beq  MODE_A
cmp  #$42
beq  MODE_B
cmp  #$43
beq  MODE_C
cmp  #$56
beq  MODE_V
cmp  #$57
beq  MODE_W
    cmp  #$51
    beq  MODE_Q
bra  DONE_RCV

```

```

MODE_A
    clr  txcnt          ; Send back all real-time variables
    lda  #$01
    sta  txmode
    lda  #$17
    sta  txgoal
    bset TE,SCC2        ; Enable Transmit
    bset SCTIE,SCC2     ; Enable transmit interrupt
    bra  DONE_RCV

```

```

MODE_B:
    mov  #$CC,flocker ;Destination ← Source
    jsr  BURNER
    clr  flocker
    clr  txmode
    bra  DONE_RCV

```

```

MODE_C:
    clr  txcnt          ; Just send back SECL variable to test comm port
    lda  #$01
    sta  txmode
    lda  #$2
    sta  txgoal
    bset TE,SCC2        ; Enable Transmit
    bset SCTIE,SCC2     ; Enable transmit interrupt
    bra  DONE_RCV

```

```

MODE_V:
    clr  txcnt
    lda  #$03
    sta  txmode
    lda  #$7E
    sta  txgoal
    bset TE,SCC2        ; Enable Transmit
    bset SCTIE,SCC2     ; Enable transmit interrupt
    bra  DONE_RCV

```

```

MODE_W:
    lda  #$05
    sta  txmode
    bra  DONE_RCV

```

```

MODE_Q:
    clr  txcnt          ; Just send back SECL variable to test comm port
    lda  #$05
    sta  txmode

```

```

lda    #$2
sta    txgoal
bset   TE,SCC2      ; Enable Transmit
bset   SCTIE,SCC2   ; Enable transmit interrupt
bra    DONE_RCV

```

```

TXMODE_5:
    mov    SCDR,rxoffset ;Destination ← Source ;Destination ← Source
    inc    txmode
    bra    DONE_RCV

```

```

TXMODE_6:
    clrh
    lda    rxoffset
    tax
    lda    SCDR
    sta    VE,x
    clr    txmode
    bra    DONE_RCV

```

```

DONE_RCV
    pulh
    rti

```

*** Transmit Character Interrupt Handler *****

```

IN_SCI_TX:
    pshh
    lda    SCS1 ; Clear the SCRF bit by reading this register
    clrh
    lda    txcnt
    tax
    lda    txmode
    cmp    #$05
    beq    IN_Q_MODE
    cmp    #$01
    bne    IN_V_MODE
IN_A_OR_C_MODE:
    lda    secl,Xamong other thinks over and over again.

```

```

    bra    CONT_TX

```

```

IN_V_MODE
    lda    ve,x
    bra    CONT_TX

```

```

IN_Q_MODE
    lda    REVNUM,X

```

```

CONT_TX:
    sta    SCDR
    lda    txcnt
    inca
    sta    txcnt
    cmp    txgoal
    bne    DONE_XFER

```

```

    clr    txcnt
    clr    txgoal
    clr    txmode

```

```

bclr  TE,SCC2      ; Disable Transmit
bclr  SCTIE,SCC2   ; Disable transmit interrupt

```

DONE_XFER

```

    pulh
    rti

```

**

** Dummy ISR - just performs RTS

**

Dummy: ; Dummy vector - there just to keep the assembler happy

```

    rti

```

**

** Various functions/subroutines Follow

**

** - Ordered Table Search

** - Linear Interpolation

** - 32 x 16 divide

**

** Ordered Table Search

**

** X is pointing to the start of the first value in the table

** tmp1:2 initially hold the start of table address, then they hold the bound values

** tmp3 is the end of the table (nelements - 1)

** tmp4 is the comparison value

** tmp5 is the index result - if zero then comp value is less than beginning of table, and

** if equal to nelements then it is rail-ed at upper end

**

ORD_TABLE_FIND:

```

    clr  tmp5

```

```

    ldhx tmp1

```

```

    lda  ,x

```

```

    sta  tmp1

```

```

    sta  tmp2

```

```

;    cmp  tmp4

```

```

;    bhi  GOT_ORD_NUM

```

REENT:

```

    incx

```

```

    inc  tmp5

```

```

    mov  tmp2,tmp1 ;Destination ← Source

```

```

    lda  ,x

```

```

    sta  tmp2

```

```

    cmp  tmp4

```

```

    bhi  GOT_ORD_NUM

```

```

    lda  tmp5

```

```

    cmp  tmp3

```

```

    bne    REENT

;    inc    tmp5
;    mov    tmp2,tmp1 ;Destination ← Source
GOT_ORD_NUM:
    rts

```

```

*****

```

```

**

```

```

** Linear Interpolation - 2D

```

```

**

```

```

**      (y2 - y1)

```

```

** Y = Y1 + ----- * (x - x1)

```

```

**      (x2 - x1)

```

```

**

```

```

** tmp1 = x1

```

```

** tmp2 = x2

```

```

** tmp3 = y1

```

```

** tmp4 = y2

```

```

** tmp5 = x

```

```

** tmp6 = y

```

```

*****

```

```

LININTERP:

```

```

    clr    tmp7 ; This is the negative slope detection bit

```

```

    mov    tmp3,tmp6 ;Destination ← Source

```

```

CHECK_LESS_THAN:

```

```

    lda    tmp5

```

```

    cmp    tmp1

```

```

    bhi    CHECK_GREATER_THAN

```

```

    bra    DONE_WITH_INTERP

```

```

CHECK_GREATER_THAN:

```

```

    lda    tmp5

```

```

    cmp    tmp2

```

```

    blo    DO_INTERP

```

```

    mov    tmp4,tmp6 ;Destination ← Source ;Destination ← Source

```

```

    bra    DONE_WITH_INTERP

```

```

DO_INTERP:

```

```

    mov    tmp3,tmp6 ;Destination ← Source

```

```

    lda    tmp2

```

```

    sub    tmp1

```

```

    beq    DONE_WITH_INTERP

```

```

    psha

```

```

    lda    tmp4

```

```

    sub    tmp3

```

```

    bcc    POSINTERP

```

```

    nega

```

```

    inc    tmp7

```

```

POSINTERP:

```

```

    psha

```

```

    lda    tmp5

```

```

    sub    tmp1

```

```

    beq    ZERO_SLOPE

```

```

    pulx

```

```

    mul

```

```

    pshx

```

```

    pulh

```

```

    pulx

```

```

div

psha
lda  tmp7
bne  NEG_SLOPE
pula
add  tmp3
sta  tmp6
bra  DONE_WITH_INTERP
NEG_SLOPE:
pula
sta  tmp7
lda  tmp3
sub  tmp7
sta  tmp6
bra  DONE_WITH_INTERP
ZERO_SLOPE:
pula      ;clean stack
pula      ;clean stack
DONE_WITH_INTERP:
rts

```

```

*****
*****

```

```

*
* 32 x 16 Unsigned Divide
*
* This routine takes the 32-bit dividend stored in INTACC1.....INTACC1+3
* and divides it by the 16-bit divisor stored in INTACC2:INTACC2+1.
* The quotient replaces the dividend and the remainder replaces the divisor.
*

```

```

UDVD32 EQU *

```

```

*
DIVIDEND EQU INTACC1+2
DIVISOR EQU INTACC2
QUOTIENT EQU INTACC1
REMAINDER EQU INTACC1
*

```

```

PSHH      ;save h-reg value
PSHA      ;save accumulator
PSHX      ;save x-reg value
AIS  #-3   ;reserve three bytes of temp storage
LDA  #!32  ;
STA  3,SP   ;loop counter for number of shifts
LDA  DIVISOR      ;get divisor msb
STA  1,SP         ;put divisor msb in working storage
LDA  DIVISOR+1    ;get divisor lsb
STA  2,SP         ;put divisor lsb in working storage

```

```

*
* Shift all four bytes of dividend 16 bits to the right and clear
* both bytes of the temporary remainder location
*

```

```

MOV  DIVIDEND+1,DIVIDEND+3 ;shift dividend lsb
MOV  DIVIDEND,DIVIDEND+2   ;shift 2nd byte of dividend
MOV  DIVIDEND-1,DIVIDEND+1 ;shift 3rd byte of dividend

```

```

MOV  DIVIDEND-2,DIVIDEND  ;shift dividend msb
CLR  REMAINDER            ;zero remainder msb
CLR  REMAINDER+1          ;zero remainder lsb
*
*  Shift each byte of dividend and remainder one bit to the left
*
SHFTLP LDA  REMAINDER      ;get remainder msb
      ROLA           ;shift remainder msb into carry
      ROL  DIVIDEND+3      ;shift dividend lsb
      ROL  DIVIDEND+2      ;shift 2nd byte of dividend
      ROL  DIVIDEND+1      ;shift 3rd byte of dividend
      ROL  DIVIDEND        ;shift dividend msb
      ROL  REMAINDER+1     ;shift remainder lsb
      ROL  REMAINDER       ;shift remainder msb
*
*  Subtract both bytes of the divisor from the remainder
*
      LDA  REMAINDER+1     ;get remainder lsb
      SUB  2,SP            ;subtract divisor lsb from remainder lsb
      STA  REMAINDER+1     ;store new remainder lsb
      LDA  REMAINDER       ;get remainder msb
      SBC  1,SP            ;subtract divisor msb from remainder msb
      STA  REMAINDER       ;store new remainder msb
      LDA  DIVIDEND+3      ;get low byte of dividend/quotient
      SBC  #0              ;dividend low bit holds subtract carry
      STA  DIVIDEND+3      ;store low byte of dividend/quotient
*
*  Check dividend/quotient lsb. If clear, set lsb of quotient to indicate
*  successful subtraction, else add both bytes of divisor back to remainder
*
      BRCLR 0,DIVIDEND+3,SETLSB ;check for a carry from subtraction
                                   ;and add divisor to remainder if set
      LDA  REMAINDER+1     ;get remainder lsb
      ADD  2,SP            ;add divisor lsb to remainder lsb
      STA  REMAINDER+1     ;store remainder lsb
      LDA  REMAINDER       ;get remainder msb
      ADC  1,SP            ;add divisor msb to remainder msb
      STA  REMAINDER       ;store remainder msb
      LDA  DIVIDEND+3      ;get low byte of dividend
      ADC  #0              ;add carry to low bit of dividend
      STA  DIVIDEND+3      ;store low byte of dividend
      BRA  DECRMT          ;do next shift and subtract

SETLSB BSET  0,DIVIDEND+3    ;set lsb of quotient to indicate
                                   ;successive subtraction
DECRMT DBNZ  3,SP,SHFTLP    ;decrement loop counter and do next
                                   ;shift
*
*  Move 32-bit dividend into INTACC1.....INTACC1+3 and put 16-bit
*  remainder in INTACC2:INTACC2+1
*
      LDA  REMAINDER       ;get remainder msb
      STA  1,SP            ;temporarily store remainder msb
      LDA  REMAINDER+1     ;get remainder lsb
      STA  2,SP            ;temporarily store remainder lsb
      MOV  DIVIDEND,QUOTIENT ;
      MOV  DIVIDEND+1,QUOTIENT+1 ;shift all four bytes of quotient
      MOV  DIVIDEND+2,QUOTIENT+2 ; 16 bits to the left

```

```

MOV  DIVIDEND+3,QUOTIENT+3 ;
LDA  1,SP                  ;get final remainder msb
STA  INTACC2                ;store final remainder msb
LDA  2,SP                  ;get final remainder lsb
STA  INTACC2+1              ;store final remainder lsb
*
* Deallocate local storage, restore register values, and return from
* subroutine
*
AIS  #3                    ;deallocate temporary storage
PULX                    ;restore x-reg value
PULA                    ;restore accumulator value
PULH                    ;restore h-reg value
RTS                      ;return
*****

```

```

*****
**
** FLASH Programming Routine
** Copied into RAM and executed there
*****

```

; Erase VE and Constants in FLASH - 128 byte erase

ERASE_N_BURN:

```

lda  flocker
cmp  #$CC
beq  ERASE_CONT
rts

```

ERASE_CONT:

```

ldhx  #FLCR
lda  #%00000010
sta  ,x ; Set erase bit
lda  FLBPR ; Read block protect register
sta  VETABLE ; Write to any address in page to be erased
lda  #$0C ; Delay 10 us
bsr  DELAYE
lda  #%00001010
sta  ,x ; set HVEN
lda  #$F0 ; 200 us
bsr  DELAYE
bsr  DELAYE
bsr  DELAYE
bsr  DELAYE
bsr  DELAYE ; total of 1 ms
lda  #%00001000
sta  ,x ; clear erase bit
lda  #$06
bsr  DELAYE ; 5 us
lda  #$00000000
sta  ,x ; clear HVEN
lda  #$02
bsr  DELAYE

```

```
bra    VE_BURNER
```

```
DELAYE:
```

```
deca
bne    DELAYE
rts
```

```
; Now Burn VE (you can only freakin burn 64 bytes at a time)
```

```
VE_BURNER
```

```
lda    #%00000001
sta    ,x    ; Set PGM bit
lda    FLBPR    ; read from FLASH block protect register
sta    VETABLE ; wrte to any address within pgmed range
lda    #$0C
bsr    DELAYVE
lda    #%00001001
sta    ,x    ; HVEN set
lda    #$06    ;
bsr    DELAYVE    ; 5 us
clrh
clrx
```

```
LOOP_TO_BURN_VE:
```

```
lda    VE,x
sta    VETABLE,x
lda    #$22    ; 28 us, everything else takes 2 us => 30 us total
bsr    DELAYVE
incx
cpx    #$40
beq    SD1
bra    LOOP_TO_BURN_VE
```

```
SD1:
```

```
ldhx    #FLCR
lda    #%00001000
sta    ,x
lda    #$06
bsr    DELAYVE
lda    #%00000000
sta    ,x
lda    #$01
bsr    DELAYVE
bra    BURN_C
```

```
DELAYVE:
```

```
deca
bne    DELAYVE
rts
```

```
; Now Burn COnstants
```

```
BURN_C:
```

```
lda    #%00000001
sta    ,x    ; Set PGM bit
lda    FLBPR    ; read from FLASH block protect register
sta    CWUTABLE ; wrte to any address within pgmed range
lda    #$0C
bsr    DELAYC
lda    #%00001001
sta    ,x    ; HVEN set
lda    #$06    ;
bsr    DELAYC    ; 5 us
```

```

        clrh
        clrx
LOOP_TO_BURN_C:
        lda    CWU,x
        sta    CWUTABLE,x
        lda    #$22    ; 28 us, everything else takes 2 us => 30 us total
        bsr    DELAYC
        incx
        cpx    #$40
        beq    SD2
        bra    LOOP_TO_BURN_C
SD2:
        ldhx   #FLCR
        lda    #%00001000
        sta    ,x
        lda    #$06
        bsr    DELAYC
        lda    #%00000000
        sta    ,x
        lda    #$01
        bsr    DELAYC
        rts    ; Exit from all of the burn routine
DELAYC:
        deca
        bne    DELAYC
        rts
DONE_C:

```

```

*****
**
** Computation of Normalized Variables
**
** The following is the form of the evaluation for the normalized variables:
**
** (A rem A * B)
** ----- = C rem C
**    100
**
** Where A = Whole part of the percentage,
**    rem A = Remainder of A from previous calculation (range 0 to 99)
**    B = Percentage multiplied (this always has a zero remainder)
**    C = Whole part of result
**    rem C = remainder of result
**
**
** Calculation is preformed by the following method:
**
** |(A * B) + (rem A * B)|
** |-----|
** |      100      |
** ----- = C rem C
**    100
**
**
** Inputs: tmp10 = A

```

```

**      tmp11 = rem A
**      tmp12 = B
**
** Outputs: tmp10 = C
**      tmp11 = rem C
**      tmp13 = high order part of (A rem A) * B
**      tmp14 = low order part of (A rem A) * B
**

```

Supernorm:

```

      lda      tmp10 ;A
      tax
      lda      tmp12 ;B
      mul
      stx      tmp13 ;High order of A * B
      sta      tmp14 ;Low order of A * B

      lda      tmp11 ;rem A
      tax
      lda      tmp12 ;B
      mul
      pshx
      pulh
      ldx      #$64 ;100
      div

      adc      tmp14 ;Add to lower part
      sta      tmp14 ;Store back
      bcc      Roundrem ;Branch is no carry occurred
      inc      tmp13 ;Increment high-order part because an overflow occurred in add

```

Roundrem:

```

      pshh
      pula
      cmp      #$32 ;Round if division remainder is greater than 50
      ble      FinalNorm
      lda      tmp14
      adc      #$01
      sta      tmp14
      bcc      FinalNorm
      inc      tmp13

```

FinalNorm:

```

      lda      tmp13
      psha
      pulh
      lda      tmp14
      ldx      #$64 ;100
      div
      bcs      RailCalc
      sta      tmp10
      pshh
      pula
      sta      tmp11

      cmp      #$32 ;Round if division remainder is greater than 50
      ble      ExitSN

```

```

lda  tmp11
adc  #$01
sta  tmp11
bcc  ExitSN
lda  tmp10
add  #$01
sta  tmp10
bne  ExitSN

```

```

RailCalc:
    mov  #$FF,tmp10    ;Rail value if rollover ;Destination ← Source

```

```

ExitSN:
    rts

```

```

;-----

```

```

org  $FAC3 ; start of bootloader-defined jump table/vector
db  $12    ; scbr regi init value
db  %00000001 ; config1
db  %00000001 ; config2
dw  {rom_start + 128} ; megasquirt code start
dw  $FB00   ; bootloader start

```

```

; Vector table
;      org      vec_timebase

```

```

db  $CC
dw  Dummy ;Timebase
db  $CC
dw  ADCDONE      ;ADC Conversion Complete
db  $CC
dw  Dummy ;Keyboard pin
db  $CC
dw  IN_SCI_TX     ;SCI transmission complete/transmitter empty
db  $CC
dw  IN_SCI_RCV    ;SCI input idle/receiver full
db  $CC
dw  Dummy ;SCI parity/framing/noise/receiver_overflow error
db  $CC
dw  Dummy ;SPI Transmitter empty
db  $CC
dw  Dummy ;SPI mode/overflow/receiver full
db  $CC
dw  TIMERROLL    ;TIM2 overflow
db  $CC
dw  Dummy ;TIM2 Ch1
db  $CC
dw  Dummy ;TIM2 Ch0
db  $CC
dw  Dummy ;TIM1 overflow
db  $CC
dw  Dummy ;TIM1 Ch1
db  $CC

```

```

        dw      Dummy ;TIM Ch0
db      $CC
        dw      Dummy ;CGM
db      $CC
        dw      DOSQUIRT;IRQ
db      $CC
        dw      Dummy ;SWI
db      $CC
        dw      Start

```

; Lookup Tables

```

org      $F100
        include "barofactor4115.inc"
        include "barofactor4250.inc"
include "kpafactor4115.inc"
include "kpafactor4250.inc"
include "thermfactor.inc"
include "airdenfactor.inc"

```

;Numbers that end with a T are explicitly in decimal format.

```

org      $E000

```

; Initial VE table, copied into RAM at startup

VETABLE:

```

db      39T    ; VE (0,0)
db      40T    ; VE (0,1)
db      41T    ; VE (0,2)
db      44T    ; VE (0,3)
db      44T    ; VE (0,4)
db      44T    ; VE (0,5)
db      45T    ; VE (0,6)
db      45T    ; VE (0,7)
db      47T    ; VE (1,0)
db      47T    ; VE (1,1)
db      51T    ; VE (1,2)
db      51T    ; VE (1,3)
db      50T    ; VE (1,4)
db      50T    ; VE (1,5)
db      50T    ; VE (1,6)
db      50T    ; VE (1,7)
db      52T    ; VE (2,0)
db      55T    ; VE (2,1)
db      55T    ; VE (2,2)
db      57T    ; VE (2,3)
db      60T    ; VE (2,4)
db      61T    ; VE (2,5)
db      61T    ; VE (2,6)
db      65T    ; VE (2,7)
db      59T    ; VE (3,0)
db      60T    ; VE (3,1)
db      60T    ; VE (3,2)
db      65T    ; VE (3,3)
db      66T    ; VE (3,4)
db      70T    ; VE (3,5)
db      70T    ; VE (3,6)
db      70T    ; VE (3,7)
db      61T    ; VE (4,0)
db      63T    ; VE (4,1)

```

db 65T ; VE (4,2)
 db 65T ; VE (4,3)
 db 68T ; VE (4,4)
 db 70T ; VE (4,5)
 db 72T ; VE (4,6)
 db 75T ; VE (4,7)
 db 65T ; VE (5,0)
 db 72T ; VE (5,1)
 db 72T ; VE (5,2)
 db 74T ; VE (5,3)
 db 74T ; VE (5,4)
 db 75T ; VE (5,5)
 db 75T ; VE (5,6)
 db 77T ; VE (5,7)
 db 70T ; VE (6,0)
 db 74T ; VE (6,1)
 db 74T ; VE (6,2)
 db 75T ; VE (6,3)
 db 75T ; VE (6,4)
 db 77T ; VE (6,5)
 db 77T ; VE (6,6)
 db 78T ; VE (6,7)
 db 75T ; VE (7,0)
 db 77T ; VE (7,1)
 db 79T ; VE (7,2)
 db 82T ; VE (7,3)
 db 82T ; VE (7,4)
 db 82T ; VE (7,5)
 db 82T ; VE (7,6)
 db 85T ; VE (7,7)

CWUTABLE:

db 120T ; CWU
 db 040T ; CWH
 db 35T ; AWEV
 db 250T ; AWC
 db 180T ; WWU (-40 F)
 db 180T ; WWU (-20 F)
 db 160T ; WWU (0 F)
 db 150T ; WWU (20 F)
 db 135T ; WWU (40 F)
 db 125T ; WWU (60 F)
 db 113T ; WWU (80 F)
 db 108T ; WWU (100 F)
 db 102T ; WWU (130 F)
 db 100T ; WWU (160 F)
 db 20T ; TPSAQ (tpsdot=0.1)
 db 50T ; TPSAQ (tpsdot=0.4)
 db 105T ; TPSAQ (tpsdot=0.8)
 db 150T ; TPSAQ (tpsdot=1.5)
 db 90T ; TPSACOLD (ms to add in when cold)
 db 03T ; TPSTHRESH
 db 02T ; TPSASYNC (accel enrich time in 1/10 second increments)
 db 100T ; TPSDQ
 db 200T ; EGOTEMP
 db 16T ; EGOCOUNTCMP
 db 1T ; EGODELTA
 db 15T ; EGOLIMIT
 db 155T ; REQFUEL

```

db 4T ; DIVIDER
db 1T ; Alternate
db 10T ; INJOPEN
db 0T ; INJOCFUEL
db 75T ; INJPWM
db 255T ; INJPWMT
db 12T ; BATTFAC
db $05 ; RPMK[0]
db $DC ; RPMK[1]

```

RPMRANGEVEFLASH:

```

db 5T ; RPMRANGEVE[0]
db 10T ; RPMRANGEVE[1]
db 15T ; RPMRANGEVE[2]
db 20T ; RPMRANGEVE[3]
db 28T ; RPMRANGEVE[4]
db 36T ; RPMRANGEVE[5]
db 44T ; RPMRANGEVE[6]
db 52T ; RPMRANGEVE[7]

```

KPARANGEVEFLASH:

```

db 20T ; KPARANGEVE[0]
db 30T ; KPARANGEVE[1]
db 40T ; KPARANGEVE[2]
db 50T ; KPARANGEVE[3]
db 60T ; KPARANGEVE[4]
db 75T ; KPARANGEVE[5]
db 90T ; KPARANGEVE[6]
db 100T ; KPARANGEVE[7]
db 113T ; Config11
db 112T ; Config12
db 00T ; Config13
db 20T ; PRIMEP
db 13T ; RPMOXLIMIT
db 185T ; FAST IDLE TEMPERATURE
db 26T ; VOLTOXTARGET
db 100T ; ACCELMULT
db 00T ; BLANK[3]
db 00T ; BLANK[4]
db 00T ; BLANK[5]
db 00T ; BLANK[6]

```

; This is used to set the bin coolant range for WWU

WWURANGE:

```

db 0T
db 20T
db 40T
db 60T
db 80T
db 100T
db 120T
db 140T
db 170T
db 200T

```

tpsdotrate:

```

db 05T ; 0.1 volts delta
db 20T ; 0.4 volt delta

```

db 40T ; 0.8 volt
db 77T ; 1.5 volt

REVNUM: db 20T ; Revision 3.000
Signature db 32T, ' ** V3.000Embedded Code by B&G **'

include "boot_r12.asm"

end

Some MegaSquirt® Variables

ACMULT = Acceleration cold multiplication factor (percent/100)
adssel = ADC Selector Variable
aircor = Air density correction is computed from MAT.
asecount = Counter value for after-start enrichment counter - every ignition
AWC = After-start number of cycles
AWEV = After-start Warmup Percent enrichment add-on value
baro = The barometric pressure as measured by MegaSquirt.
barocor = Barometer Lookup Correction - percent, based on the initial MAP sensor reading.
batt = Battery Voltage ADC Raw Reading - counts
BATTFAC = Battery Gamma Factor
clt = Coolant Temperature ADC Raw Reading - counts (0 - 255)
coolant = Coolant temperature in Degrees F plus 40 (allows -40 degrees to fit in integer)
CWH = Crank Enrichment at 170 F
CWU = Crank Enrichment at -40 F
ddra = Port A Data Direction Register
ego = Exhaust Gas Oxygen ADC Raw Reading - counts
egocorr = This is the correction factor computed from O2 sensor readings.
egocount = Counter value for EGO step - incremented every ignition pulse
egotemp = Coolant Temperature where EGO is active
egocountcmp = Counter value where EGO step is to occur
egodelta = EGO Percent step size for rich/lean
egolimit = Upper/Lower EGO rail limit (egocorr is inside 100 +/- Limit)
engine = Variable bit-field to hold engine current status
FASTIDLE = Fast Idle Temperature
gammae = Total Gamma Enrichments - percent
InjOpen = Injector Open Time
InjOCFuel = PW-correlated amount of fuel injected during injector open
INJPWM = Injector PWM duty cycle at current limit
INJPWMT = Injector PWM millisec time at which to activate.
kpa = MAP value in units of KPa
KPARANGEVE = VE Table MAP Pressure Bins for 2_D interpolation
last_tps = TPS reading updated every 0.1 seconds
lmap = Manifold Absolute Pressure ADC last Reading
lmat = Manifold Air Temp ADC last Reading
lclt = Coolant Temperature ADC last Reading
ltps = Throttle Position Sensor ADC last Reading
lbatt = Battery Voltage ADC last Reading
lego = Last EGO ADC reading
map = Manifold Absolute Pressure ADC Raw Reading - kPa (0 - 255)
mat = Manifold Air Temp ADC Raw Reading - counts (0 - 255)
mms = 0.0001 second update variable
ms = 0.001 second increment
porta = Port A Data Register
portb = Port B Data Register
portc = Port C Data Register

PRIMEP = Priming pulses (0.1 millisec units)
 pulseigncount = Ignition pulse counter
 pw = The injector pulse width being used by MS to squirt fuel into your motor.
 pwcalc = Computed pulse width - move into variable PW at pulse time
 pw = Injector squirt time in 1/10 milliseconds (0 to 25.5 millisec) - applied
 pw2 = The other PW comparison (injector #2)
 pwrn1 = Pulse width timing variable 1 - from 0 to 25.5ms
 pwrn2 = Pulse width timing variable 2 - from 0 to 25.5ms
 REQ_FUEL = Fuel Constant
 RPMOXLIMIT = Minimum RPM where O2 Closed Loop is Active
 rpm = Computed engine RPM - rpm/100
 rpmch = Counter for high part of RPM
 rpmcl = Counter for low part of RPM
 rpmp1 = Low part of RPM Period
 rpmk = Constant for RPM = 12,000/ncyl - downloaded constant
 rpmp1h = High part of RPM Period
 rpmp1h = last rpmp1h value (for odd-fire)
 rpmp1l = last rpmp1l value (for odd-fire)
 RPMRANGEVE = VE table RPM Bins for 2-D interpolation
 rxoffset = offset placeholder when receiving VE/constants vis. SCI
 secl = Time in seconds since MegaSquirt last booted. Low seconds - from 0 to 255, then rollover.
 sech = High seconds - rollover at 65536 secs (1110.933 minutes, 18.51 hours)
 squirt = Event variable bit field for Injector Firing.
 tenth = 1/10th second
 tmp1,...,tmp19 = Temporary storage.
 tps = Throttle Position Sensor ADC Raw Reading - counts, represents 0 - 5 volts
 tpsaccel = The acceleration enrichment.
 tpsack = TPS enrichment timer clock in 0.1 second resolution
 TPSAQ = TPS acceleration amount (fn TPSDOT) in 0.1 ms units
 tpsacold = Cold acceleration amount (at -40 degrees) in 0.1 ms units
 TPSASYNC = ***** TPS Acceleration clock value
 TPSDQ = Deacceleration fuel cut
 tpsfuelcut = TPS Fuel Cut (percent).
 tpsthresh = Accel TPS DOT threshold
 txcnt = SCI transmitter count (incremented)
 txgoal = SCI number of bytes to transmit
 txmode = Transmit mode flag
 T1SCX_NO_PWM = No PWM
 VE = 64 bytes for VE Table
 vecurr = The current computed VE value determined by look up in the VETABLE using RPM and MAP.
 VOLTOXTARGET = O2 sensor flip target value
 warmcor = The warmup correction factor applied due to startup and coolant temperature status.
 WWU = Warmup bins(fn temp)

MegaSquirt 68HC908GP32 Memory Map

\$0000 - \$003F = I/O Registers: 64 Bytes
 \$0040 - \$023F = RAM 512
 \$0240 - \$7FFF = Unimplemented 32,192 bytes
 \$8000 - \$FDFF = FLASH Memory: 32,256 bytes
 \$FE00 = SIM Break Status Register (SBSR)
 \$FE01 = SIM Reset Status Register (SRSR)
 \$FE02 = Reserved (SUBAR)
 \$FE03 = SIM Break Flag Control Register (SBFCR)
 \$FE04 = Interrupt Status Register 1 (INT1)
 \$FE05 = Interrupt Status Register 2 (INT2)
 \$FE06 = Interrupt Status Register 3 (INT3)
 \$FE07 = Reserved (FLTCR)

\$FE08 = FLASH Control Register
\$FE09 = Break Address Register High (BRKH)
\$FE0A = Break Address Register Low (BRKL)
\$FE0B = Break Status And Control Register (BRKSCR)
\$FE0C = LVI Status Register (LVISR)
\$FE0D - \$FE0F = Unimplemented: 3 bytes
\$FE10 - \$FE1F = Unimplemented: 16 bytes Note: Reserved for compatibility with monitor code for A-Family parts
\$FE20 - \$FF52 = Monitor ROM: 307 bytes
\$FF53 - \$FF7D = Unimplemented: 43 bytes
\$FF7E = Flash Block Protect Register (FLBPR)
\$FF7F - \$FFDB = Unimplemented: 93 bytes
\$FFDC - \$FFFF = Flash Vectors: 36 bytes

Instruction set:

ADC = Add with Carry
ADD = Add without Carry
AIS = Add Immediate Value (Signed) to Stack Pointer
AIX = Add Immediate Value (Signed) to Index Register
AND = Logical AND
ASL = Arithmetic Shift Left
ASR = Arithmetic Shift Right
BCC = Branch if Carry Bit Clear
BCLR n = Clear Bit n in Memory
BCS = Branch if Carry Bit Set
BEQ = Branch if Equal
BGE = Branch if Greater Than or Equal To
BGT = Branch if Greater Than
BHCC = Branch if Half Carry Bit Clear
BHCS = Branch if Half Carry Bit Set
BHI = Branch if Higher
BHS = Branch if Higher or Same
BIH = Branch if IRQ Pin High
BIL = Branch if IRQ Pin Low
BIT = Bit Test
BLE = Branch if Less Than or Equal To
BLO = Branch if Lower
BLS = Branch if Lower or Same
BLT = Branch if Less Than
BMC = Branch if Interrupt Mask Clear
BMI = Branch if Minus
BMS = Branch if Interrupt Mask Set
BNE = Branch if Not Equal
BPL = Branch if Plus
BRA = Branch Always
BRA = Branch Always
BRCLR n = Branch if Bit n in Memory Clear
BRN = Branch Never
BRSET n = Branch if Bit n in Memory Set
BSET n = Set Bit n in Memory
BSR = Branch to Subroutine
CBEQ = Compare and Branch if Equal
CLC = Clear Carry Bit
CLI = Clear Interrupt Mask Bit
CLR = Clear
CMP = Compare Accumulator with Memory
COM = Complement (One's Complement)

CPHX = Compare Index Register with Memory
CPX = Compare X (Index Register Low) with Memory
DAA = Decimal Adjust Accumulator
DAA = Decimal Adjust Accumulator (Continued)
DBNZ = Decrement and Branch if Not Zero
DEC = Decrement
DIV = Divide
EOR = Exclusive-OR Memory with Accumulator
INC = Increment
JMP = Jump
JSR = Jump to Subroutine
LDA = Load Accumulator from Memory
LDHX = Load Index Register from Memory
LDX = Load X (Index Register Low) from Memory
LSL = Logical Shift Left
LSR = Logical Shift Right
MOV = Move
MUL = Unsigned Multiply
NEG = Negate (Two's Complement)
NOP = No Operation
NSA = Nibble Swap Accumulator
ORA = Inclusive-OR Accumulator and Memory
PSHA = Push Accumulator onto Stack
PSHH = Push H (Index Register High) onto Stack
PSHX = Push X (Index Register Low) onto Stack
PULA = Pull Accumulator from Stack
PULH = Pull H (Index Register High) from Stack
PULX = Pull X (Index Register Low) from Stack
ROL = Rotate Left through Carry
ROR = Rotate Right through Carry
RSP = Reset Stack Pointer
RTI = Return from Interrupt
RTS = Return from Subroutine
SBC = Subtract with Carry
SEC = Set Carry Bit
SEI = Set Interrupt Mask Bit
STA = Store Accumulator in Memory
STHX = Store Index Register
STOP = Enable IRQ Pin, Stop Oscillator
STX = Store X (Index Register Low) in Memory
SUB = Subtract
SWI = Software Interrupt
TAP = Transfer Accumulator to Processor Status Byte
TAX = Transfer Accumulator to X (Index Register Low)
TPA = Transfer Processor Status Byte to Accumulator
TST = Test for Negative or Zero
TSX = Transfer Stack Pointer to Index Register
TXA = Transfer X (Index Register Low) to Accumulator
TXS = Transfer Index Register to Stack Pointer
WAIT = Enable Interrupts; Stop Processor